

WHAT IS CLAIMED IS:

1 1. A method of configuring a direction-based Core Based Tree (CBT) for a CBT-based
2 overlay multicast, the method comprising:

3 requesting and receiving information on child nodes pre-subscribed to a core node at an
4 arbitrary terminal node to be subscribed to the CBT;

5 calculating a direction between the terminal node and each of the child nodes and
6 transmitting information on the child node having a minimum resultant value to the core node
7 along with a subscription request message; and

8 comparing the calculated direction between a corresponding child node and the terminal
9 node with the calculated direction between child nodes pre-subscribed to the core node at the core
10 node and subscribing the terminal node to either the child node or a parent node of the
11 corresponding child node in accordance with the comparison to configure the CBT.

1 2. The method according to claim 1, further comprising periodically transmitting and
2 receiving a hello packet at the core node and the terminal node to and from the parent node, the
3 child node and a brother node to confirm a state of the corresponding node and reconfiguring the
4 configured CBT in response to the confirmed state of the corresponding node.

1 3. The method according to claim 1, wherein calculating the direction comprises using
2 internal and external angles and a height of a triangle having respective distances between the core

node and two arbitrary nodes adjacent to the core as respective sides of the triangle.

4. The method according to claim 3, wherein calculating the direction comprises using the formula:

$$\text{direction} = (\alpha + \beta) * y$$

wherein the triangle has nodes a1, C0 and a2, C0 being a core node, and a1 and a2 being arbitrary nodes, C0 and a2 forming a bottom side of the triangle, “ α ” being an internal angle formed by a side C0a1 and a side C0a2 of the triangle; “ β ” being an external angle formed by the side C0a1 and a side a1a2 of the triangle, “y” being a height of the triangle, and “direction” being the calculated direction.

5. The method according to claim 1, wherein calculating the direction further comprises determining that the child node having a minimum resultant value and the terminal node have a same forwarding direction of packets from the core node, the terminal node being determined to be either a child node or a parent node of the corresponding child node

6. The method according to claim 1, wherein:
when the resultant value of calculating the direction between the corresponding child node and the terminal node is smaller than the resultant value of calculating the direction between the pre-subscribed child nodes at the core node, the terminal node is subscribed to the child node of the core node and a message is transmitted to the pre-subscribed child node to re-subscribe to the

child node of the terminal node; and

the pre-subscribed child node withdraws from the core node and subscribes to the child node of the terminal node in response to the message.

7. A program storage device, readable by a machine, tangibly embodying a program of instructions executable by the machine to perform a method of configuring a direction-based Core Based Tree (CBT) for a CBT-based overlay multicast, the method comprising:

requesting and receiving information on child nodes pre-subscribed to a core node at an arbitrary terminal node to be subscribed to the CBT;

calculating a direction between the terminal node and each of the child nodes and transmitting information on the child node having a minimum resultant value to the core node along with a subscription request message; and

comparing the calculated direction between a corresponding child node and the terminal node with the calculated direction between child nodes pre-subscribed to the core node at the core node and subscribing the terminal node to either the child node or a parent node of the corresponding child node in accordance with the comparison to configure the CBT.

8. The program storage device according to claim 7, the method further comprising periodically transmitting and receiving a hello packet at the core node and the terminal node to and from the parent node, the child node and a brother node to confirm a state of the corresponding node and reconfiguring the configured CBT in response to the confirmed state of the

5 corresponding node.

1 9. The program storage device according to claim 7, wherein calculating the direction
2 comprises using internal and external angles and a height of a triangle having respective distances
3 between the core node and two arbitrary nodes adjacent to the core as respective sides of the
4 triangle.

1 10. The program storage device according to claim 9, wherein calculating the direction
2 comprises using the formula:

3
$$\text{direction} = (\alpha + \beta) * y$$

4 wherein the triangle has nodes a1, C0 and a2, C0 being a core node, and a1 and a2 being
5 arbitrary nodes, C0 and a2 forming a bottom side of the triangle, “ α ” being an internal angle
6 formed by a side C0a1 and a side C0a2 of the triangle; “ β ” being an external angle formed by the
7 side C0a1 and a side a1a2 of the triangle, “y” being a height of the triangle, and “direction” being
8 the calculated direction.

1 11. The program storage device according to claim 7, wherein calculating the direction
2 further comprises determining that the child node having a minimum resultant value and the
3 terminal node have a same forwarding direction of packets from the core node, the terminal node
4 being determined to be either a child node or a parent node of the corresponding child node.

1 12. The program storage device according to claim 7, wherein:
2 when the resultant value of calculating the direction between the corresponding child node
3 and the terminal node is smaller than the resultant value of calculating the direction between the
4 pre-subscribed child nodes at the core node, the terminal node is subscribed to the child node of
5 the core node and a message is transmitted to the pre-subscribed child node to re-subscribe to the
6 child node of the terminal node; and
7 the pre-subscribed child node withdraw from the core node and subscribes to the child node
8 of the terminal node in response to the message.